

## Quiz – Lab2: Robot Remote Control

1. What type of commutation connections is used between Sparki robot and remote controller?
  - a. USB cable connection
  - b. Ethernet cable connection
  - \*c. Wireless connection
  - d. Bluetooth connection
2. How many processes involved in remote control of Sparki robot?
  - a. 7
  - b. 6
  - c. 5
  - \*d. 4
3. When Saprki robot receives a signal from remote controller, which data type it will decode into?
  - \*a. integer
  - b. float
  - c. character
  - d. string
4. Which one is not one of vulnerabilities of wireless communication?
  - a. eavesdropping
  - b. interference
  - c. noise
  - \*d. accessibility